

Supervised HSMM to study the behavioral sequences of wildlife in nature from accelerometer data.

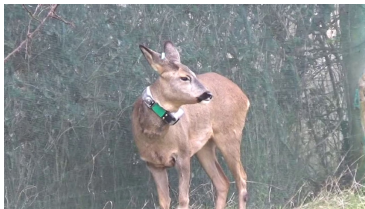
Sandra Plancade, Nathalie Peyrard

(Applied Mathematics and Informatics, INRAE, Toulouse)

Nicolas Morellet, Nathan Ranc

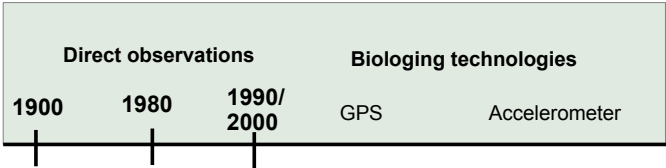
(Center of wildlife study, INRAE, Toulouse)

MASEMO - 1st-4th July 2025



Behavioral ecology

How animals behave to satisfy their fundamental needs



				
Amount of data	weak	good	very good	
Precision of information on behavior	very good	gross	very fine scale but limited methods	

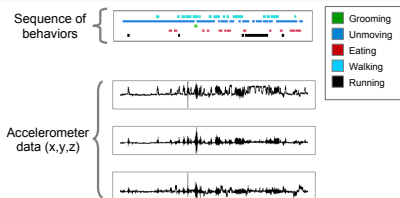
- 1 Accelerometer data analysis
- 2 General HSMM framework for sequence analysis
- 3 Where are we now?
- 4 Modified Viterbi : balance between adequation to the model and to the observations
- 5 Metric for sequence comparison
- 6 Conclusion

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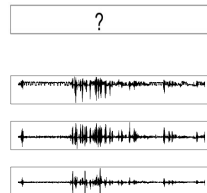
Supervised framework

- Captive animals : videos $\sim$ 10 minutes + accelerometer (32hz)
- Wild animals : accelerometer $\sim$ months

Observed animals



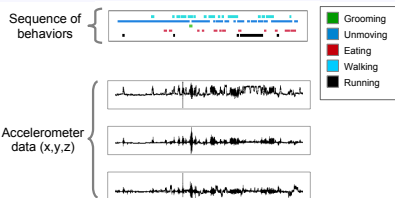
Unobserved animals



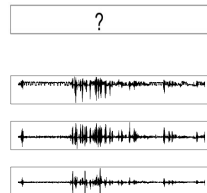
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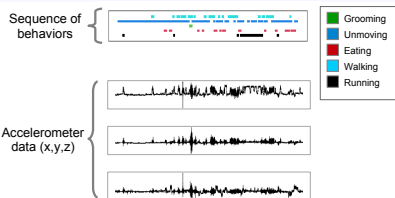
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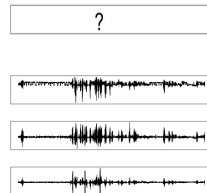
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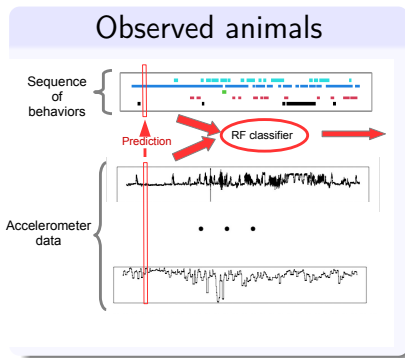
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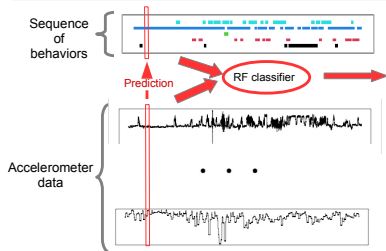


Classic method : Time-by-time classification

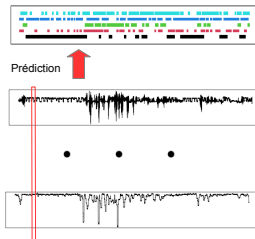


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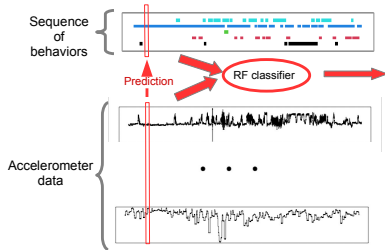


Unobserved animals

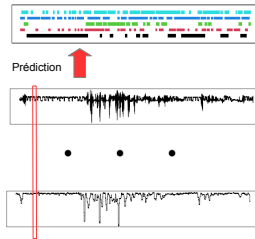


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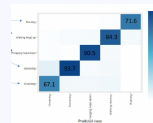


Output

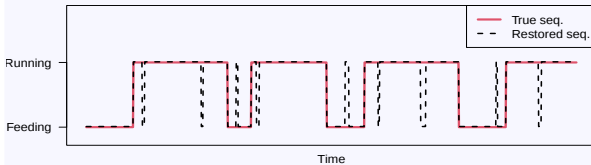
Time budget



Model evaluation = accuracy

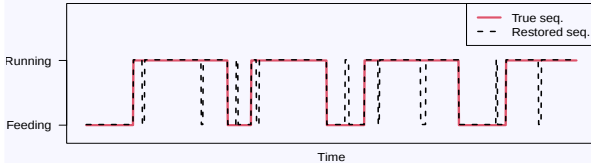


Good accuracy $\neq$ good sequence restoration



- Accuracy : 0.95
- Wrong transitions
- Wrong very short durations

Good accuracy $\neq$ good sequence restoration



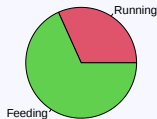
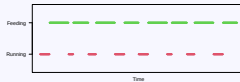
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Why sequence analysis?

Forest landscape

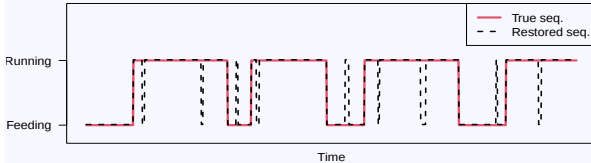


Open landscape



- Different dynamics
- Same time budget

Good accuracy $\neq$ good sequence restoration



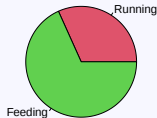
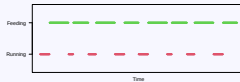
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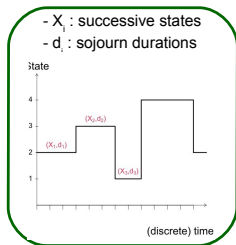


- Different dynamics
- Same time budget

$\Rightarrow$ HSMM : account for behavior durations and transitions

Hidden Semi-Markov Models

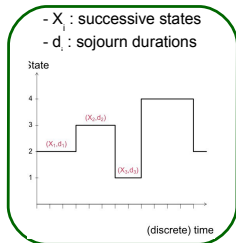
SMM



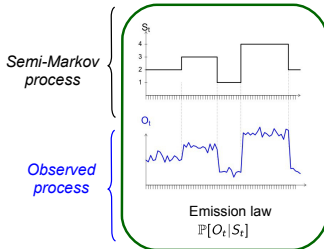
$$\mathbb{P}[(X_{i+1}, d_{i+1}) | (X_i, d_i), \cancel{(X_{i-1}, d_{i-1})}, \dots, \cancel{(X_1, d_1)}] \stackrel{\text{ED}}{=} \mathbb{P}[d_{i+1} | X_{i+1}] \mathbb{P}[X_{i+1} | X_i]$$

Hidden Semi-Markov Models

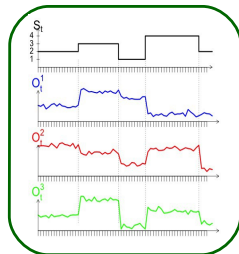
SMM



HSMM



multiresponse HSMM

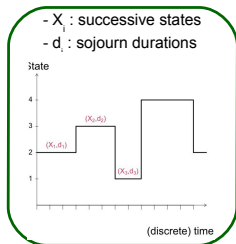


$$\mathbb{P}[(X_{i+1}, d_{i+1}) | (X_i, d_i), \cancel{(X_{i-1}, d_{i-1})}, \dots, \cancel{(X_1, d_1)}] \stackrel{\text{ED}}{=} \mathbb{P}[d_{i+1} | X_{i+1}] \mathbb{P}[X_{i+1} | X_i]$$

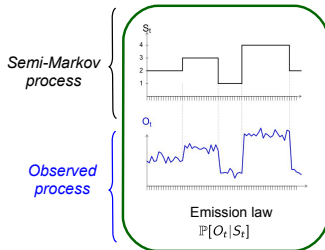
$$\mathbb{P}[(O_t)_t | (S_t)_t] = \prod_t \mathbb{P}[O_t | S_t]$$

Hidden Semi-Markov Models

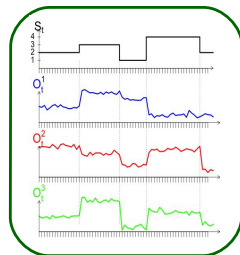
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$$\mathbb{P}[(X_{i+1}, d_{i+1}) | (X_i, d_i), \cancel{(X_{i-1}, d_{i-1})}, \dots, \cancel{(X_1, d_1)}] \stackrel{\text{ED}}{=} \mathbb{P}[d_{i+1} | X_{i+1}] \mathbb{P}[X_{i+1} | X_i]$$

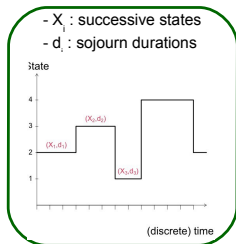
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Parameters (Explicit Duration)

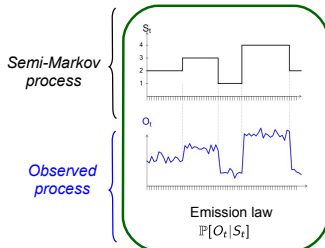
- Emission $\mathbb{P}_{\Theta}[O_t | S_t]$
- Sojourn duration $\mathbb{P}_{\Theta}[d_i | X_i]$
- Transition $\mathbb{P}_{\Theta}[E_{i+1} | X_i]$

Hidden Semi-Markov Models

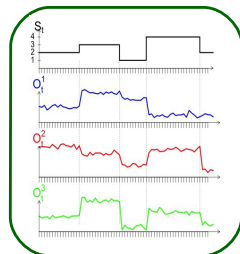
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HSMM



multiresponse HSMM



$$\mathbb{P}[(X_{i+1}, d_{i+1}) | (X_i, d_i), \cancel{(X_{i-1}, d_{i-1})}, \dots, \cancel{(X_1, d_1)}] \stackrel{\text{ED}}{=} \mathbb{P}[d_{i+1} | X_{i+1}] \mathbb{P}[X_{i+1} | X_i]$$

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Parameters (Explicit Duration)

- Emission $\mathbb{P}_\Theta[O_t | S_t]$
- Sojourn duration $\mathbb{P}_\Theta[d_i | X_i]$
- Transition $\mathbb{P}_\Theta[X_{i+1} | X_i]$

Issues

- Parameter estimation Θ
- Restoration of hidden sequence, e.g. Viterbi

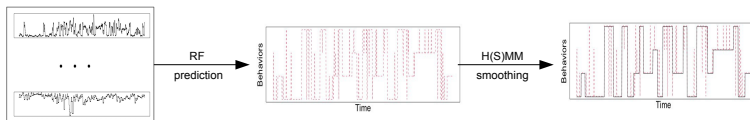
$$\arg \max_{(S_t)_{t \geq 1}} \mathbb{P}[(S_t)_{t \geq 1} | (O_t)_{t \geq 1}, \Theta]$$

H(S)MM for accelerometer data

- In literature
 - ▶ HMM more frequent than HSMM

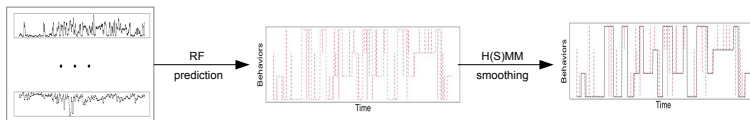
H(S)MM for accelerometer data

- In literature
 - ▶ HMM more frequent than HSMM
 - ▶ Observed variables : two strategies
 - ★ A/few selected feature(s) function of accelerometer (x,y,z)
 - ★ H(S)MM for smoothing RF predictions



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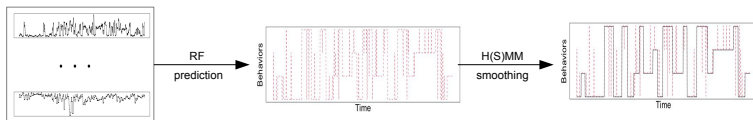


- ▶ Output = time budget/ accuracy /classification $\neq$ sequence analysis

H(S)MM for accelerometer data

- In literature

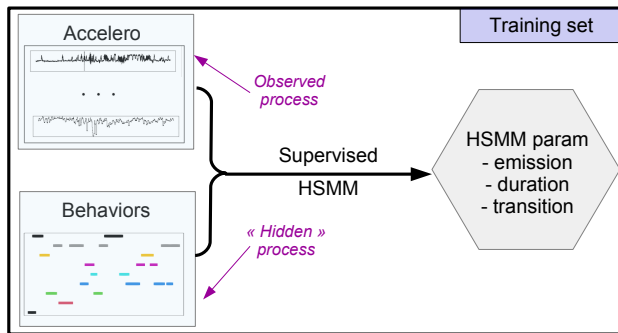
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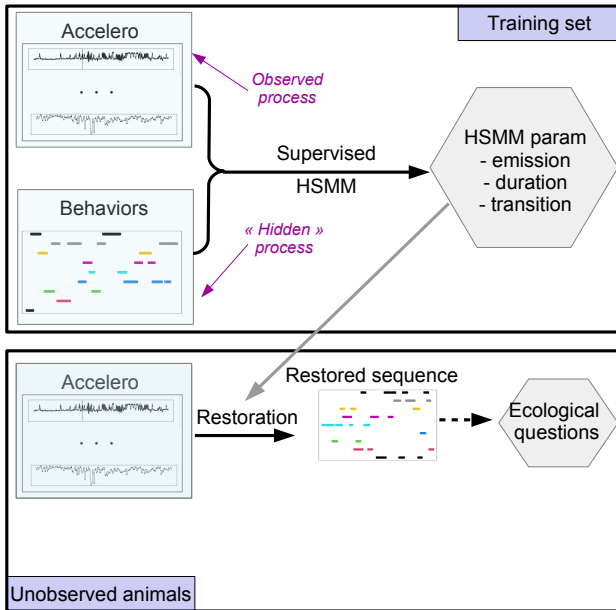
- ▶ Output = time budget/ accuracy /classification $\neq$ sequence analysis
- ▶ A few alternative works
 - ★ Koslik *et al* (2025) : Inhomogeneous Markov models with interest on sojourn time distribution

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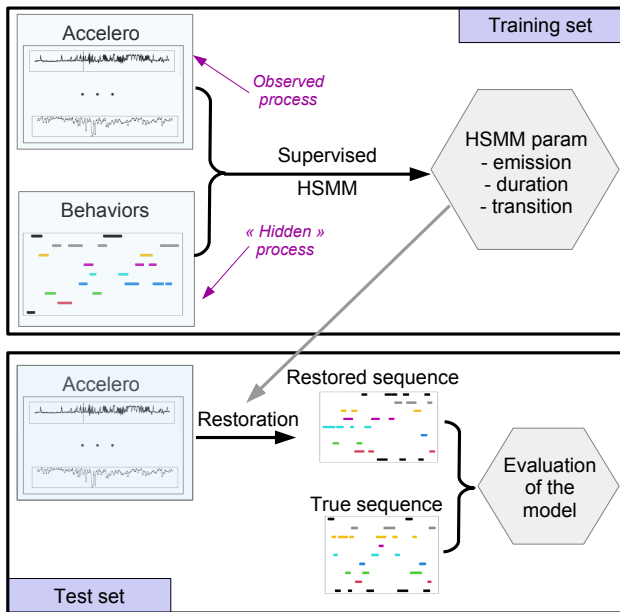
General statistical framework



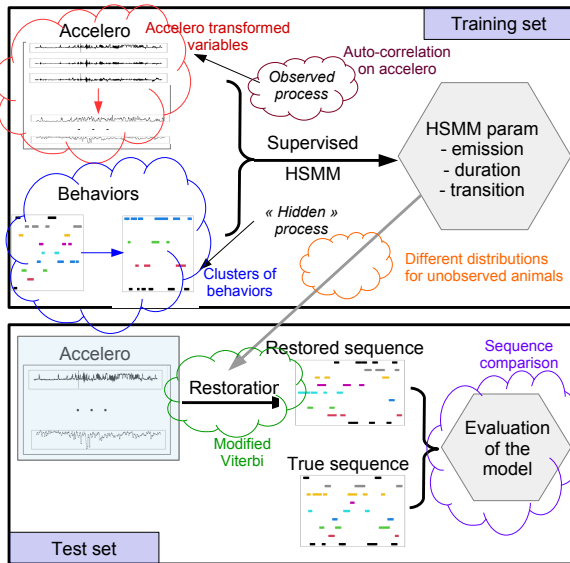
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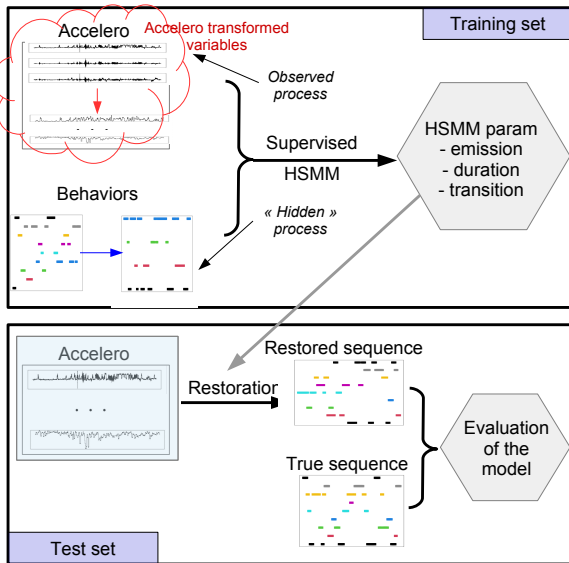


Various issues



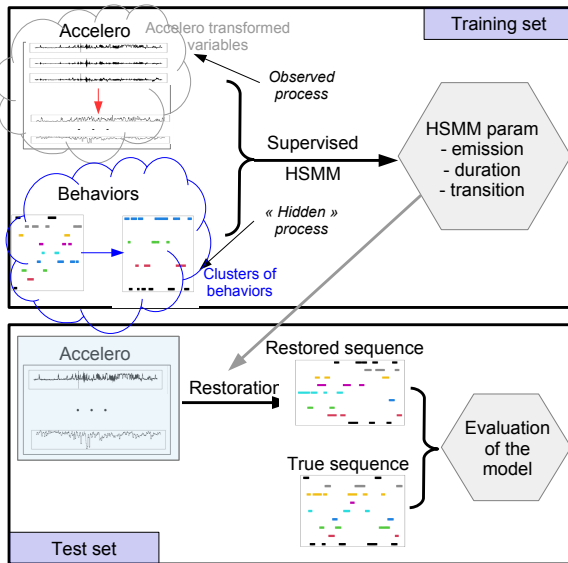
- Which accelerometer features
- Level of details of behaviors
- Autoregressive model for accelerometer data
- Modified Viterbi
- Metric for sequence similarity
- Robustness/transferability

Various issues



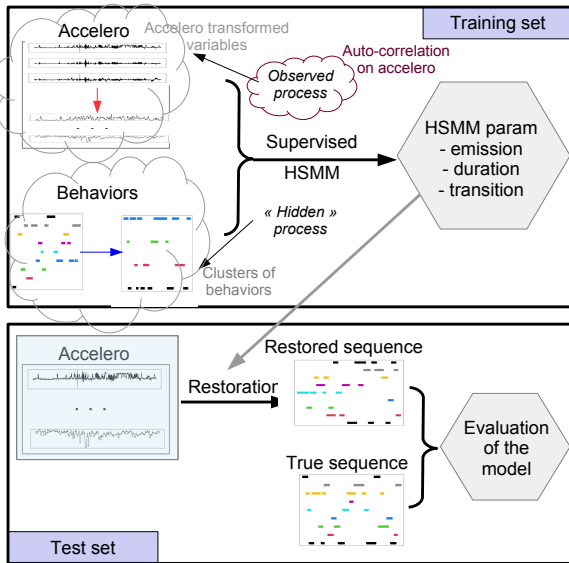
- Which accelerometer features
 - ▶ Balance complexity and discriminative power
- Level of details of behaviors
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Various issues



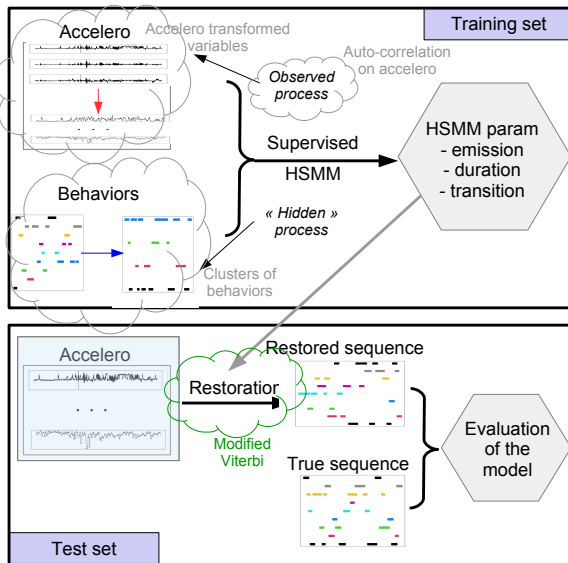
- Which accelerometer features
- Level of details of behaviors
 - ▶ distinguishable
 - ▶ interpretable
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Various issues



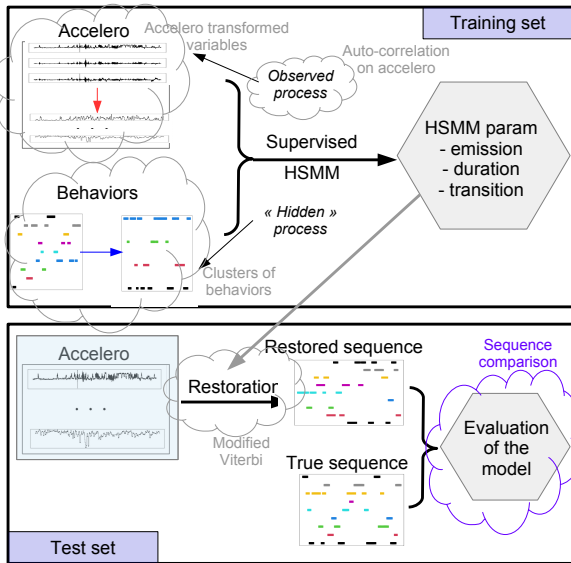
- Which accelerometer features
- Level of details of behaviors
- Autoregressive model for accelerometer data
 - ▶ Independent observations: unrealistic
 - ▶ HSMM-AR
- Modified Viterbi
- Metric for sequence similarity
- Robustness/transferability

Various issues



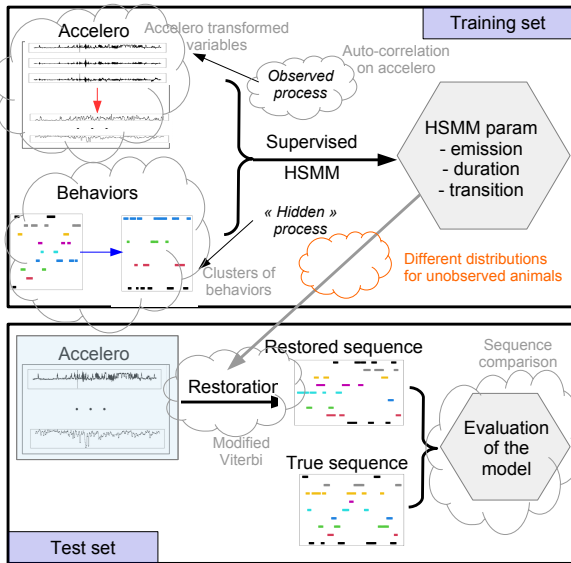
- Which accelerometer features?
- Level of details of behaviors
- Autoregressive model for accelerometer data
- **Modified Viterbi**
- Metric for sequence similarity
- Robustness/transferability

Various issues



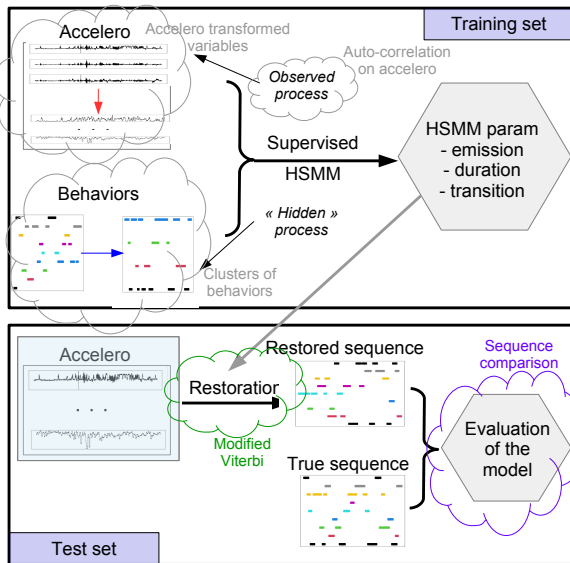
- Which accelerometer features
- Level of details of behaviors
- Autoregressive model for accelerometer data
- Modified Viterbi
- Metric for sequence similarity
 - ▶ What is a good restoration?
 - ▶ Also for hyperparameter calibration by CV
- Robustness/transferability

Various issues



- Which accelerometer features
- Level of details of behaviors
- Autoregressive model for accelerometer data
- Modified Viterbi
- Metric for sequence similarity
- **Robustness/transferability**
 - ▶ difference of behavior captive/wild animals

Various issues



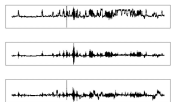
- Which accelerometer features
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- **Modified Viterbi**
- **Metric for sequence similarity**
- Robustness/transferability

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Model choices

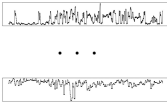
- "Observed" process = RF prediction

(x,y,z) accelerometer data



Variable
transformation

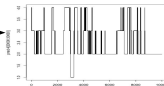
26 interpretable features



Improved accuracy but
too complex emission law

RF
prediction

« Observed » process



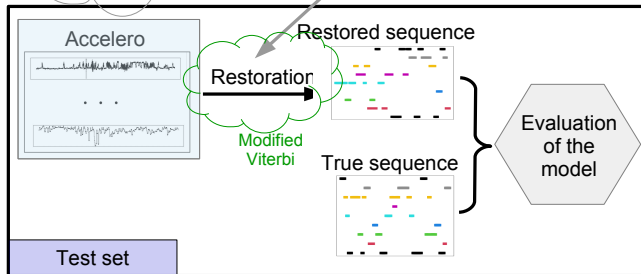
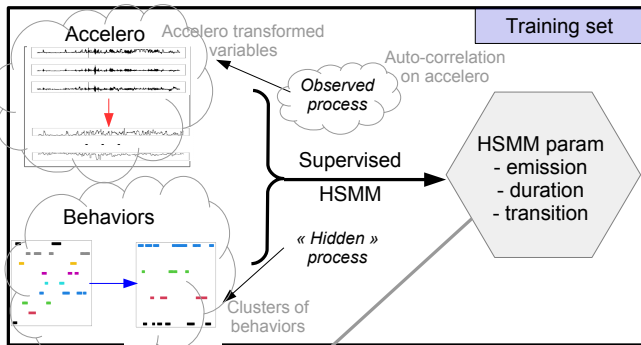
Emission : discrete
distribution

- 4 states $\leftrightarrow$ 4 clusters of behaviors
- Independent accelerometer observations
- Restoration by a modified version of Viterbi

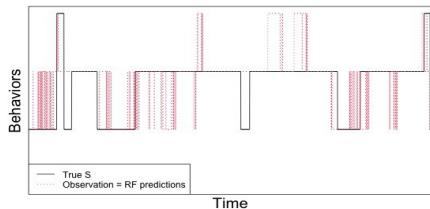
Results

- Unsufficient quality of restoration for sequence-by-sequence analysis
 - ▶ Limits of the model but also of the information contained in the data
- Alternative goal : comparison between conditions (e.g. day/night)
 - ▶ Not done yet

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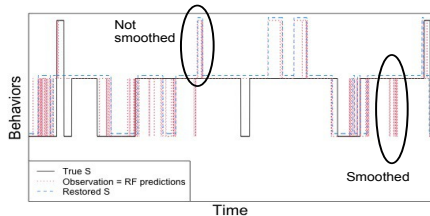


Restored sequences by Viterbi



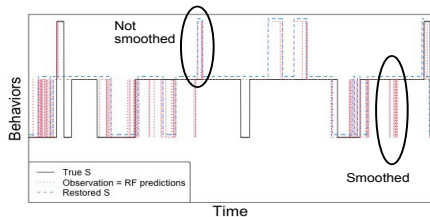
- RF : many wrong transitions and brief sojourns

Restored sequences by Viterbi



- RF : many wrong transitions and brief sojourns
- HSMM : partially smooth

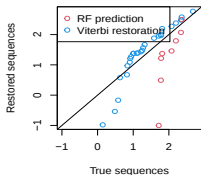
Restored sequences by Viterbi



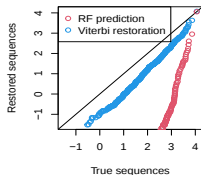
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True and restored sojourn duration

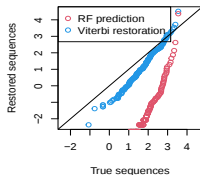
Behavior 1 (n=27)



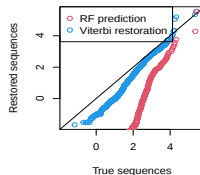
Behavior 2 (n=532)



Behavior 3 (n=160)



Behavior 4 (n=631)



- Over-representation of brief sojourn durations in restored sequences
 - Brief sojourn durations unlikely given SMM parameters
- ⇒ Too much adequation to the observed process

Adequation to the model and to the observations

- Viterbi algorithm targets the most probable hidden sequence

$$\arg \max_S \log \mathbb{P}_\Theta[S|O] = \arg \max_S \left\{ \underbrace{\log \mathbb{P}_\Theta[O|S]}_{\substack{\text{adequation} \\ \text{to observations}}} + \underbrace{\log \mathbb{P}_\Theta[S]}_{\substack{\text{adequation} \\ \text{to model}}} + \cancel{\log \mathbb{P}_\Theta[O]} \right\}$$

Adequation to the model and to the observations

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$$\arg \max_S \log \mathbb{P}_\Theta[S|O] = \arg \max_S \left\{ \underbrace{\log \mathbb{P}_\Theta[O|S]}_{\substack{\text{adequation} \\ \text{to observations}}} + \underbrace{\log \mathbb{P}_\Theta[S]}_{\substack{\text{adequation} \\ \text{to model}}} + \cancel{\log \mathbb{P}_\Theta[O]} \right\}$$

- **Modify the balance** between adequation to the observations and to the model

$$\arg \max_S \{ (1 - \lambda) \log \mathbb{P}_\Theta[O|S] + \lambda \log \mathbb{P}_\Theta[S] \} \quad \text{with} \quad \lambda > 1$$

Adequation to the model and to the observations

- Viterbi algorithm targets the most probable hidden sequence

$$\arg \max_S \log \mathbb{P}_\Theta[S|O] = \arg \max_S \left\{ \underbrace{\log \mathbb{P}_\Theta[O|S]}_{\substack{\text{adequation} \\ \text{to observations}}} + \underbrace{\log \mathbb{P}_\Theta[S]}_{\substack{\text{adequation} \\ \text{to model}}} + \cancel{\log \mathbb{P}_\Theta[O]} \right\}$$

- **Modify the balance** between adequation to the observations and to the model

$$\arg \max_S \{ (1 - \lambda) \log \mathbb{P}_\Theta[O|S] + \lambda \log \mathbb{P}_\Theta[S] \} \quad \text{with} \quad \lambda > 1$$

- Select λ by cross-validation on the training set : which λ leads to the best restoration?
 - ▶ **Metric for sequence comparison**

(Digressive) remark: impact of sampling frequency on Viterbi

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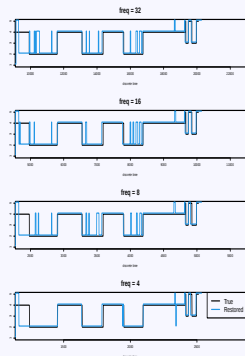
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Undersampling
accelerometer data



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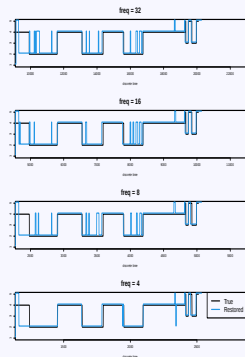
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⇒ Modified Viterbi is not only an artefact, it may also compensate the arbitrary choice of sampling frequency

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$$\begin{cases} S = (S_t)_{t=1:T} & = \text{true behaviour sequence} \\ \hat{S} = (\hat{S}_t)_{t=1:T} & = \text{restored behaviour sequence} \end{cases}$$

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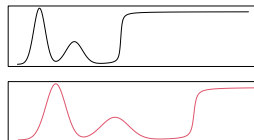


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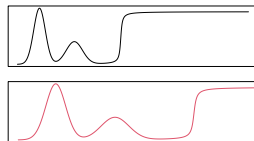


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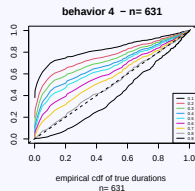
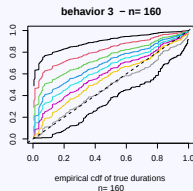
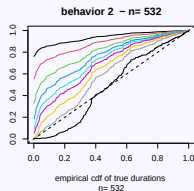
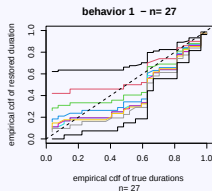
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- ▶ Tractable algorithm
- Similarity adapted to behavior sequence analysis?
 - ▶ Up to now : no lead for a sequence-by-sequence comparison
 - ▶ Compare duration and transitions **distributions**

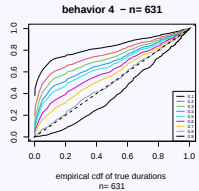
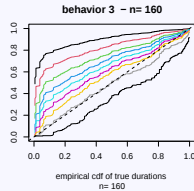
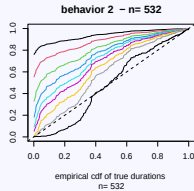
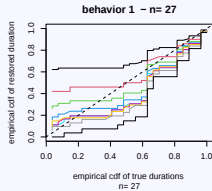
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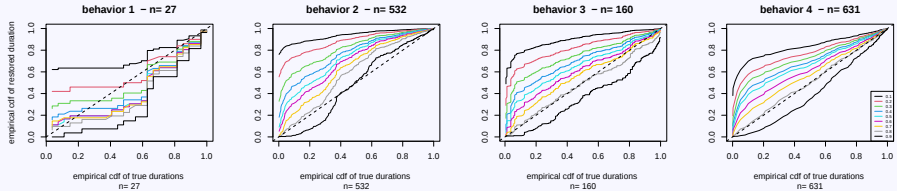


Limits

- Best λ may depends on the behavior class.
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